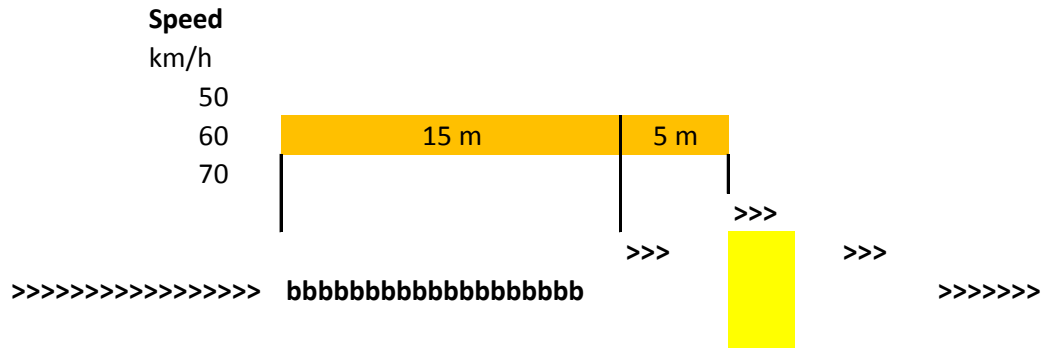


BRAKING AND EVASIVE MOVEMENT



> = drive
b = brake